Phase field modeling of interfacial dynamics

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Collaborators

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 Microstructure evolution in superalloy MatCASE (NSF-DMR-ITR) and CCMD (NSF-IUCRC)
- Chun Liu, Jian Zhang, Peng Yu, Margret Slattery,
 Jiakou Wang, Tianjiang Li, Manlin Li, Meghan Hentry,
 Rob Kunz, Cheng Dong and Susan Gilmor (PSU)
 Xiaoqiang Wang (FSU), Rolf Ryham (Rice)
 Complex/biological fluids
 NSF-DMS, NSF-CISE



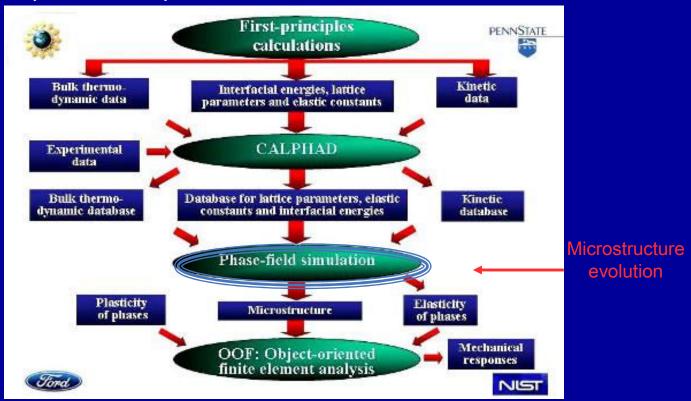
Outline

- Motivation (materials, biology, ...)
- Derivation of phase field models
- Examples based on recent works
- Adaptive numerical algorithms



Motivation: MatCASE

http://matcase.psu.edu



Atomic structure

grid enabled data intensive simulation tool

Liu-Chen-Raghavan-Du-Sofo-Langer-Wolverton, 2004: *An integrated Framework for multi-scale materials simulation and design,* J. Computer Aided Materials Design

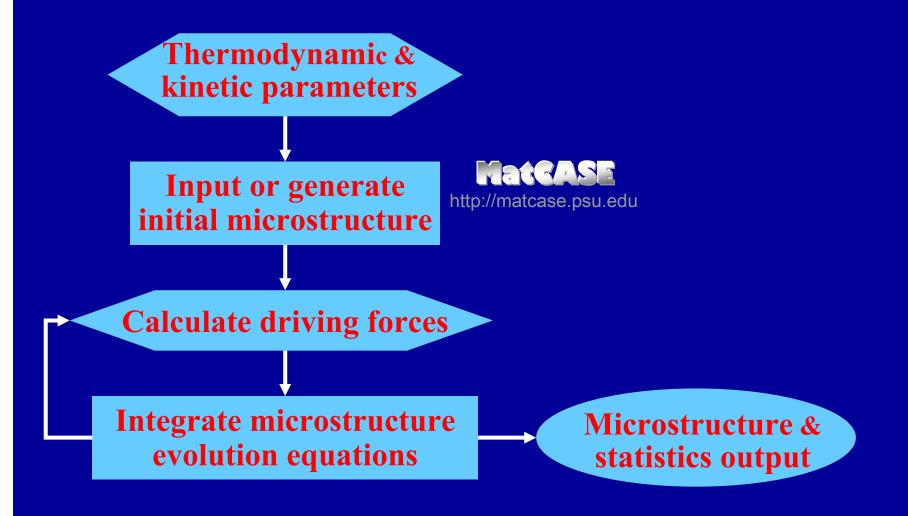
Phase Field/Diffuse Interface Modeling

- Popular for simulations of free and moving interface problems in materials sciences and other applications
- Sharp interfaces → diffuse interfaces characterized by some phase field function

Eg: phase field simulations of microstructure evolution in ferroelectric thin films (Yu-Hu-Chen-Du, JCP 2005)

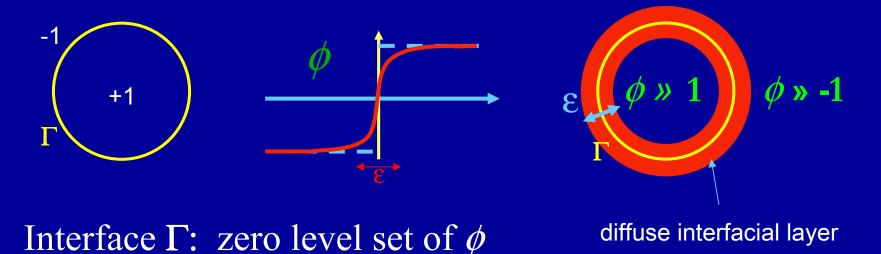
• Idea goes back to van de Waals, Ginzburg-Landau, Cahn-Hilliard, Halperin-Hohenberg, ...

Phase-Field simulation of microstructure Evolution



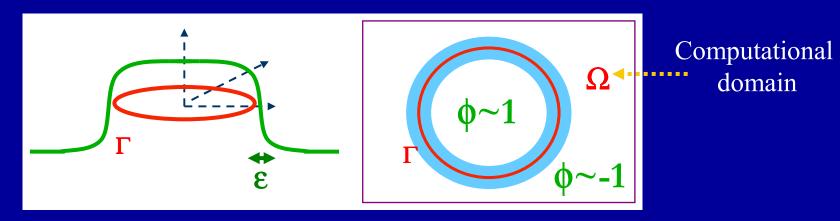
Diffuse Interface/Phase Field

• Geometric illustration: introducing a smooth but nearly piecewise constant phase field function ϕ to label the two sides of the interface Γ .



Diffuse interface/Phase field

• How to describe the geometric features of Γ by ϕ ?



Volume (difference):
$$A(\phi) = \int_{\Omega} \phi \ dx$$

Area:
$$B(\phi) = \int_{\Omega} \left(\frac{\epsilon}{2} |\nabla \phi|^2 + \frac{1}{4\epsilon} (\phi^2 - 1)^2 \right) dx$$

(Cahn, Modica, Sternberg, Kohn, Gurtin, Chen, Evans-Souganidis-Soner...)

What about other geometric features, interfacial/bulk physics to be described in applications?

Case Study: Vesicle Membranes

Biomimetic cell membrane: lipid vesicle

RBC

fluid bilayer formed by amphiphilic lipids

Vesicle Membrane Models

- Atomistic models: ab initio, MD
- Coarse-grained models: MC, effective particle, triangulated networks, Browning dynamics
- Continuum mechanics:
 - bending elasticity model for lipid bilayer (well-recognized, a good starting point)
- Multiscale models

Bending elasticity model

- Earlier studies: Canhem 70, Helfrich 73, Evans 79, Fung, Lipowsky, Ouyang, Miao, Waugh, Iglic, Seifert, Wortis, Dobereiner, Chadwick, Gompper, Noguchi, Guven, ...
- Hypothesis: vesicle Γ minimizes the bending elasticity energy s.t. volume/area constraints

min
$$\mathbf{E} = \int_{\Gamma} H^2 ds$$

subj. to volume/area constraints

Special case of Helfrich energy

$$H = \frac{k_1 + k_2}{2}$$
mean curvature

$$\mathbf{E} = \int_{\Gamma} (a + b(H - c_0)^2 + cG) ds$$

Studies on Bending Elasticity Model

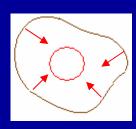
- Analytical/geometrical constructions: Helfrich, Lipowsky, Seifert, Wortis, Ouyang, Guven, ...
- Numerical simulations: FEM, triangulated networks, surface evolver, moving LS, immersed boundary, lattice Boltzmann, particle dynamics...
- Our recent works (JCP 2004, 2006, Nonlinearity 2005, SIAM Appl Math 2005, CPAA 2005, JCM 2006,):

Diffuse Interface/ Phase Field model energetic variational framework, no explicit surface tracking, allow complex topological changes, ...

Q: mean curvature of implicitly defined surface?

Phase Field Calculus

• Geometric calculus: variation of surface area/surface tension leads to mean curvature



• Translate into Phase Field calculus: variation of

$$\int_{\Omega} \left(\frac{\epsilon}{2} |\nabla \phi|^2 + \frac{1}{4\epsilon} (\phi^2 - 1)^2 \right) dx \text{ (area/surface tension)}$$

gives the expression $-\epsilon \Delta \phi + \frac{1}{\epsilon} (1 - \phi^2) \phi$

$$\int_{\Gamma} H^2 ds \iff \frac{c}{\epsilon} \int_{\Omega} \left(\epsilon \Delta \phi + \frac{1}{\epsilon} (\phi^2 - 1) \phi \right)^2 dx$$

• Similar extension to other features: spontaneous curvature, Gaussian curvature,, Du-Liu-Wamg JCP 04

Phase field bending elasticity model (PFBE)

Du-Liu-Wang JCP 2004

min
$$W(\phi) = \frac{c}{\epsilon} \int_{\Omega} (\epsilon \Delta \phi + \frac{1}{\epsilon} (\phi^2 - 1)\phi)^2 dx$$

subject to $\int_{\Omega} \phi(x) dx = \alpha$

$$\int_{\Omega} \left(\frac{\epsilon}{2} |\nabla \phi|^2 + \frac{1}{4\epsilon} (\phi^2 - 1)^2 \right) dx = \beta$$

Vesicle Γ : zero level surface of the phase field function ϕ (enclosed in the computational domain Ω)

Dynamics: 1) gradient flow:
$$\longrightarrow \frac{\partial \phi}{\partial t} = -\frac{\delta W_M}{\delta \phi}$$

Sharp interface limit of PFBE($\epsilon \rightarrow 0$)

In Du-Liu-Ryham-Wang (Nonlinearity 2005), with ansatz

$$\phi(x) = q(y) + \epsilon h(x) + O(\epsilon^2) + \dots,$$

it was shown
$$\frac{\phi(x)=tanh(\frac{y}{\sqrt{2}})+O(\epsilon^2),}{E(\phi)\to\int_\Gamma H^2d\Gamma} y=\frac{d(x,\Gamma)}{\epsilon}$$

Recently, by taking a more general ansatz

$$\phi(x)=q\left(y\right)+\epsilon h(y,x)+\epsilon^2 g(y,x)+...$$
 Wang (2006) showed
$$q(y)=\tanh(\frac{y}{\sqrt{2}}),\ h=0,$$

$$g(y,x)=r(x)s(y),\ E(\phi)\to \int_\Gamma H^2 d\Gamma$$

in addition, the variation → Willmore stress

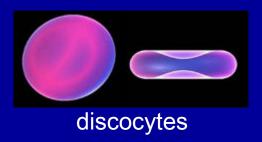
Minimum bending energy vesicles

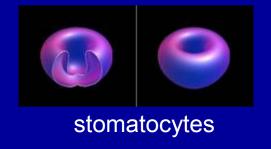
Excess area:

$$\sigma = \frac{\left(\frac{A}{4\pi}\right)^{1/2}}{\left(\frac{3}{4V\pi}\right)^{1/3}}$$

$$\sigma = 1$$
 sphere

$$\sigma > 1$$





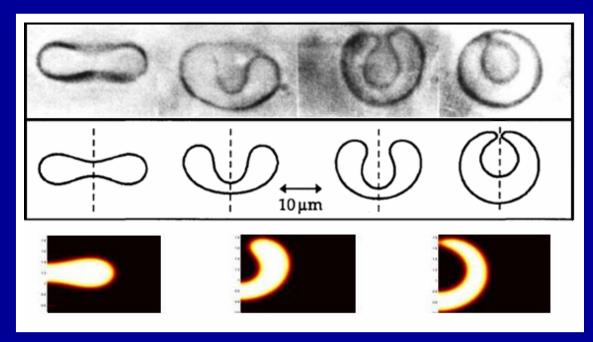






Simulation vs. Experiment

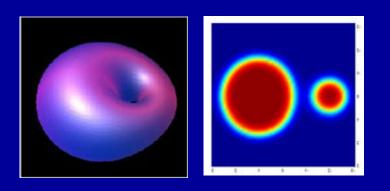
Berndl 1990: vesicle deformation in response to changing temperature 43.8-44.1°C



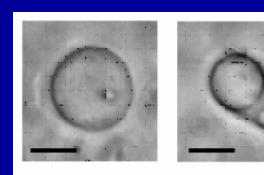
cross sections of 3d vesicles (Du-Liu-Wang JCP 2004)

Simulation vs. Experiment

• Symmetric and non-symmetric torus (full 3d)



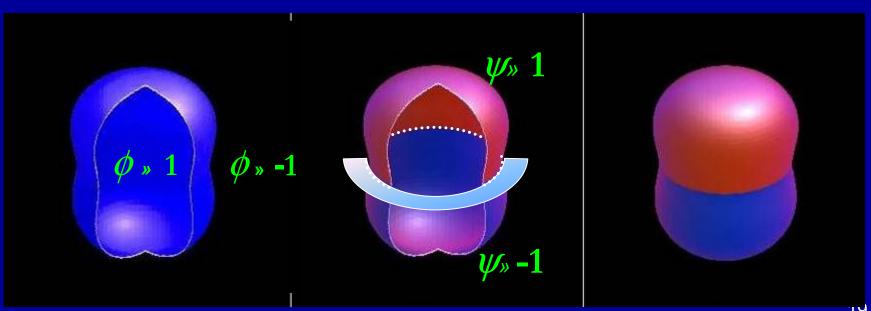




Michalet-Bensimon Theory of Ou-Yang

Multi-component vesicles

- Recent experimental studies of multicomponent membranes revealed intricate structure of rafts which are important for biological functions
- Phase field description of phase separation on a deformable membrane: multiple phase field functions + bending energy of membrane + line tension between different phases

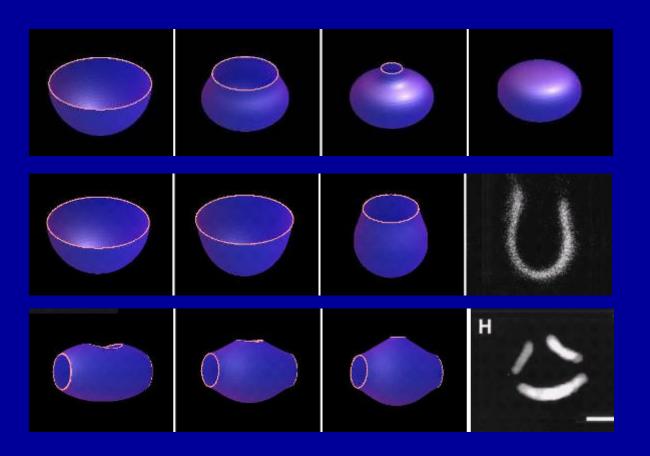


Modeling multi-component membranes

- Wang-Du 2006: Phase field model for multicomponent vesicle with bending elastic energy + line tensions + fixed total volume + fixed surface areas for individual phases
- Simulation of vesicle phase separation: raft, microdomain

Similar extension: membrane with free edges

 Treat as a two-component membrane, pick bending rigidity to be zero in one component (Wang-Du 2006)



Saitoh-Takiguchi-Tanaka-Hotani

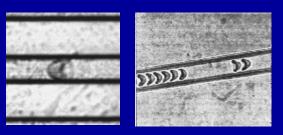
Capovilla-Guven-Santiago

Umeda-Suezaki-Takiguchi-Hotani

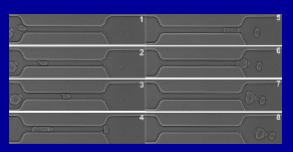
Ouyang-Tu

Phase field for interfaces in fluid

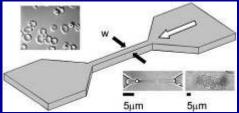
•Experimental works on RBCs/vesicles in fluid



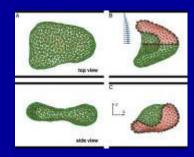
Tsukada et al 2001



Abkarian-Faivre-Stone 2006



Shelby et al 2003



Noguchi-Gompper 2005

•Modeling/simulations Keller, Lipowsky, Pozrikidis, Grompper, Noguchi, Seifert, DeHaas, Misbah, Kantsler, WK Liu, Suresh

Phase-Field Navier-Stokes Model

Du-Liu-Ryham-Wang 2005



Phase field
Allen-Cahn/Cahn-Hilliard
fluid transport



Navier-Stokes

Willmore stress

$$E'(\phi)\nabla\phi$$

A coupled vesicle/fluid model: PFNS

$$\begin{cases} \mathbf{u}_{t} + \mathbf{u} \cdot \nabla \mathbf{u} + \nabla p = \mu \Delta \mathbf{u} + E'(\phi) \nabla \phi, \\ \text{Phase-Field} \\ \nabla \cdot \mathbf{u} = 0, \\ \phi_{t} + \mathbf{u} \cdot \nabla \phi = -AE'(\phi), \quad (A = -\Delta \text{ or } I \text{ or } 0) \end{cases}$$

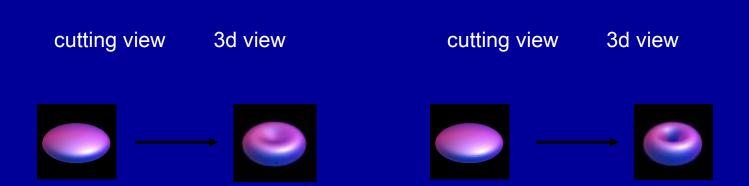
$$\frac{d}{dt} \left(\int_{\Omega} \frac{1}{2} |\mathbf{u}|^{2} d\mathbf{x} + E(\phi) \right) = -\int_{\Omega} \mu |\nabla \mathbf{u}|^{2} d\mathbf{x} \quad \text{energy} \\ \text{law} \\ -\int_{\Omega} E'(\phi) AE'(\phi) d\mathbf{x} \end{cases}$$

Similar works: Siggia-Halperin-Hohenberg, Gurtin-Polignone-Vinals, Yue-Feng-Liu-Shen, Liu-Walkington, Lowengrub-Truskinovsky, Anderson-McFadden-Wheeler,... (note: we use bending energy)

Some examples

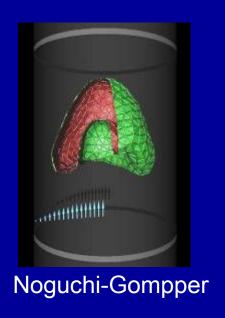
Du-Liu-Wang 2006

 Membrane/fluid interactions (single vesicle): fluid motion due to membrane deformation



Some examples

 Membrane fusion driven by fluid

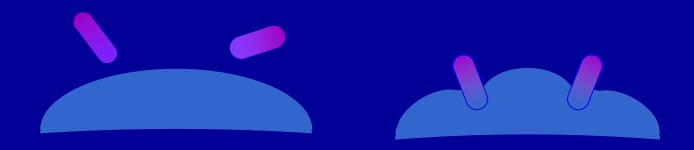


cutting view

3d view

Extension: vesicle/protein interaction

• Vesicle mediated interaction (on-going): membrane deformation due to embedded proteins, which in turn determines the force and interaction between proteins



• Protein assisted vesicle fusion (on-going)

Extension: protein + bilayer + fluid

• Membrane adhesion (on-going): bonding between ligand-receptor → Multi-scale micro-macro coupling



Phase Field/Diffuse Interface Modeling

- Simple, systematic derivation (geometry, energy, ...)
- Interface capturing (no need for explicit tracking)
- Consistent to conventional sharp interface description
- Bridge effects from multiple scales/processes
- Effective for complex interfacial dynamics

efficient numerical algorithms!

Algorithms and numerical analysis

For Allen-Cahn, Cahn-Hilliard, Phase Field

• Finite difference, Finite element

Fix/Lin, Caginalp/Lin, Elliott/French, Du/Nicolaides,

Fife/Mackenny, Chen/Hoffmann, Wang/Sekerka, Feng/Prohl,

Braun/Murray, Karma/Rappel, Provatas/Goldenfeld/Dantzig,

Anderson/McFadden/Wheeler, Garcke/Nestler/Stoth,

Mackenzie/Robertson, Wise/Lowengrub/Kim/Johnson, ...

- Spectral/Semi-implicit
 Chen/Shen, Zhu/Chen, Liu/Shen, Yue/Feng/Liu/Shen
- Spectral/Exponential time difference (ETD)

 Du/Zhu (2004, 2005): FFT based, high order in both time/space

Recent development: adaptivity

- FEM for phase field bending elasticity model
 - mixed formulation, discrete energy-law preserving gradient flow, convergence analysis (Du-Wang, IJNAM)
 - nested saddle point formulation for mixed finite elements with optimal order error estimates (Du-L.Zhu, JCM)
 - full 3D adaptive FEM implementation based on residual type posterior error estimator (Du-Zhang, SISC)
- Spectral methods for phase field models
 - Applications to phase field bending elasticity model (Du-Liu-Wang, JCP)
 - Adaptive Fourier spectral via moving mesh method (Yu-Chen-Du, DCDS; Feng-Yu-Hu-Liu-Du-Chen, JCP)

Spectral methods

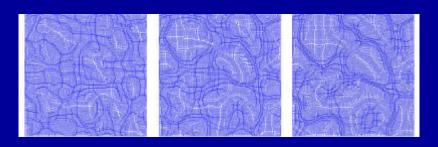
Application to phase field models (Chen-Shen 92):

- > Phase field functions are smooth with given interfacial width
- Fourier Spectral: superior accuracy, fast implementation
- Rigid Cartesian grid structure
- Accuracy degradation if the interface is under resolved

To better represent interfacial region

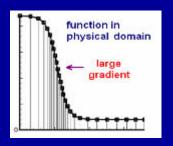
Moving mesh Fourier spectral (Yu-Du-Chen 2006, Feng-Yu-Hu-Liu-Du-Chen 2006):

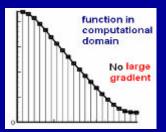
following works of Winslow, Nakashashi-Deiwert, Bayliss-Kuske-Matkowsky, Huang-Ren-Russell, Ceniceros-Hou,...)

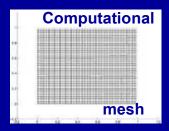


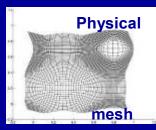
Moving Mesh/Fourier Spectral (MMFS)

(Feng-Yu-Hu-Liu-Du-Chen, JCP 2006)







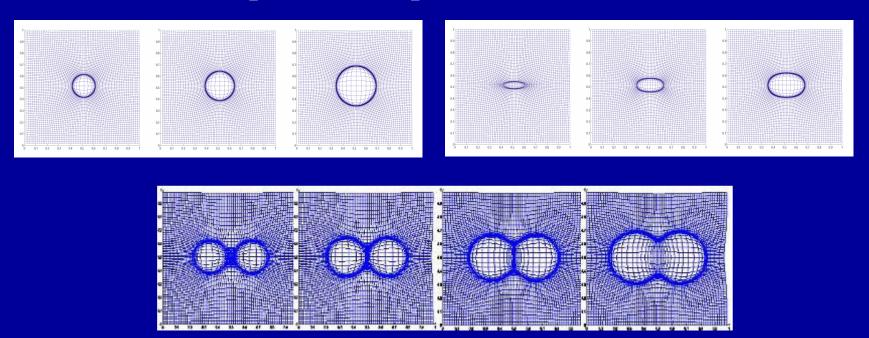


- Large gradient in physical domain requires higher resolution, leading to prohibitively fine uniform mesh
- To make grids clustered near physical interface, a mapping is introduced between physical and computational domain so that the grids remain uniform in the latter
- MMFSM (moving mesh Fourier spectral method): mesh changes with solution to provide maximum resolution in physical domain
- Overcome variable coefficients due to mesh motion to allow FFT, reduce system size and improve accuracy
- Performance gain despite of the overhead

Moving Mesh/Fourier Spectral (MMFS)

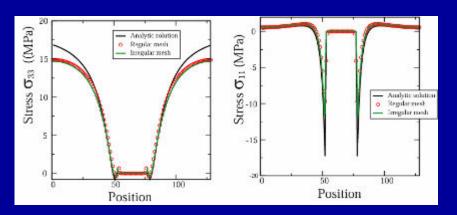
• Example: Application to Allen-Cahn model of microstructure evolution in a binary alloy

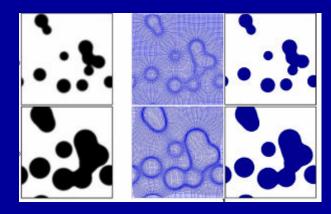
(isotropic/anisotropic cases, Yu-Chen-Du 2006)



Moving Mesh/Fourier Spectral (MMFS)

Two dimensional (Feng et al 2006)



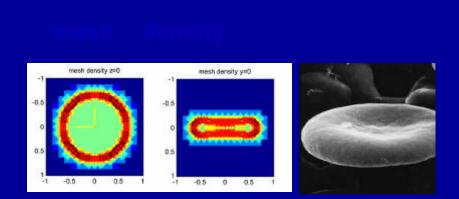


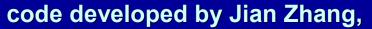
Three dimensional (Feng et al 2006)

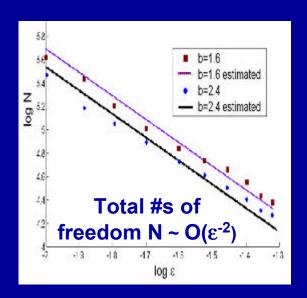
Preliminary results demonstrate the effectiveness of MMFS

Adaptive 3d FEM

- Vesicle membranes are 2-d surfaces, but phase field functions are solved in 3-d computational domain
- Adaptivity via residual a posteriori error estimates
- 3D Computation gets reduced to 2D complexity



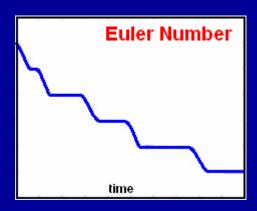




anisotropic adaptivity?

Automated topological information retrieval

- Level-set/Phase field type methods are insensitive to topological changes (advantage or deficiency?)
- Formulae are developed to detect /control topology change in shape transformation via Euler number

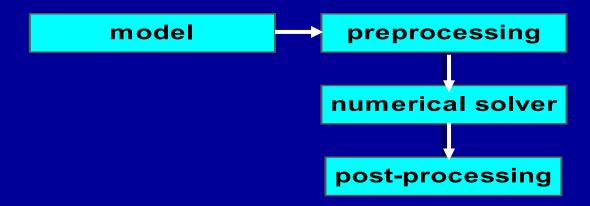


Connect geometry with topology, allow effective detection and control of topological events

2d periodic:
$$\chi = \frac{1}{4\pi\epsilon^2} \int_{\Omega} (\phi^2 - 1) \phi d\Omega$$

A larger picture

Computation in the traditional sense:



- The era of intelligent scientific computing:
 - find and simultaneously "recognize" the solution, discover new rules/principles
 - -- learning and knowledge discovery

Summary

- Diffuse interface/Phase field model can be used to simulate many problems related to interfacial dynamics, and couple multi-scale, multi-processes
- Diffuse interface approach can be efficiently implemented via mesh adaptivity, and it is shown to be very effective through comparing with experimental findings